



**FACULTY OF ELECTRICAL ENGINEERING  
AND INFORMATION SCIENCE**



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DEVICES AND SYSTEMS,  
MATERIALS AND TECHNOLOGIES  
FOR THE FUTURE**

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Susanne Jakob  
Dipl.-Ing. Helge Drumm

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J. Naumenko, V. Astakhov

## Computing of Steady and Pseudo-Steady Magnetic Fields in Presence of Ideal Conducting Surfaces

### APPLIED ELECTROMAGNETICS AND CIRCUIT THEORY

A stationary or quasi-stationary magnetic field of induction  $\vec{B}$  is examined in presence of finite multi-connected surface  $S$  with boundaries, on which condition of the ideal conductivity is satisfied:

$$\vec{B}\vec{n} = 0 \text{ on } S, \quad (1)$$

where  $\vec{n}$  is a unit vector of a normal to  $S$ .

There is potential  $\vec{A}$ :  $\text{rot} \vec{A} = \vec{B}$ ,  $\text{div} \vec{A} = 0$ . The condition (1) looks as  $\text{rot}_n \vec{A} = 0$  on  $S$ , that is  $\vec{A} = \vec{C}$  on  $S$ .  $\vec{C}$  - some field,  $\text{rot}_n \vec{C} = 0$ .

We suppose the surface and its boundaries satisfy to conditions of Lipschitz and magnetic field of the reaction has finite energy. Also we suppose the energy of nonperturbed magnetic field is bounded in some finite domain  $G$  i.e.  $\iiint_G |\vec{B}^0|^2 dG < \infty$ .

Borders of  $G$  satisfy to conditions of Lipschitz;  $S \subset G$ .

We consider the space  $L_2(S)$  of quadratically integrable complex-valued vectorial functions  $\{\vec{a}_k\}$  on  $S$ . Vectorial space  $L_2(S)$  can be decomposed on  $S$  to a sum of orthogonal subspaces:  $L_2(S) = L_2^{(\Pi)}(S) \oplus L_2^{(I)}(S) \oplus L_2^{(C)}(S)$  where  $L_2^{(\Pi)}(S)$  consists of generalized by Weyl potential fields,  $L_2^{(C)}(S)$  generalized solenoidal fields, and  $L_2^{(I)}(S)$  generalized harmonic fields [1,2]. We use space  $\mathcal{L} = L_2^{(I)}(S) \oplus L_2^{(C)}(S)$ .

We designate  $P^{(\mathcal{L})}$  the operator of orthogonal projection of  $L_2(S)$  to  $\mathcal{L}$ . Surface currents density  $\vec{\sigma}$  can be described by integral equation of the first kind [3]:

$$T\vec{\sigma} = \vec{f}, \quad (2)$$

where

$$T = P^{(\mathcal{L})} \Gamma, \quad \Gamma \vec{a}(M) = \frac{1}{4\pi} \iint_S \frac{\vec{a}(N)}{r_{NM}} dS_N,$$

$$\bar{f} = -\frac{1}{\mu} P^{(\Omega)}(\bar{A}^0 - \bar{A}^*), \quad \bar{A}^*(M) = \sum_{j=1}^m \frac{\Phi_j}{4\pi} \text{rot} \oint_{l_j} \frac{d\bar{l}_N}{r_{NM}}, \quad M \in S.$$

where  $\bar{A}^0(M)$  is a potential of the nonperturbed magnetic field of external (given)

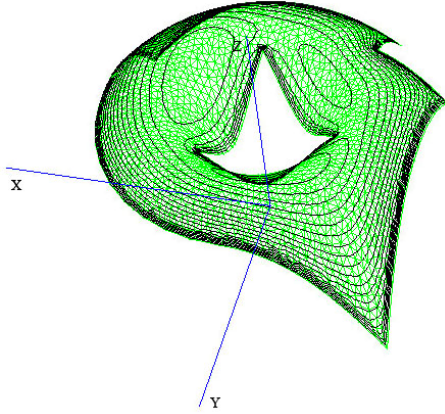


Fig. 1

sources;  $\mu$  - a magnetic permeability;  $\bar{\sigma}$  - a surface currents density;  $r_{NM}$  - distance between points  $N, M$ ,  $\Phi_i$  - given flow of magnetic field through the hole  $i$  in surface  $S$ ,  $l_i$  - some closed curve passing through the hole  $i$ .

It is possible to prove that the solution of the equation (2) does not only exist and is unique in power space  $\mathcal{L}_T$  of the operator  $T$ , but also

$$\mu \|\bar{\sigma}\|_{\mathcal{L}_T}^2 \leq \frac{1}{\mu} \iiint_{\Omega} |\bar{B}^0|^2 d\Omega. \text{ Last inequality means in}$$

particular that the error of the magnetic field energy of reaction does not exceed a similar error of the external sources field energy. The solution of the equation (2) is numerically stable in this sense.

The simple form of kernel of integral equation (2) opens broad possibilities to optimization of numerical algorithms for their solving. A software package was built on the basis of the described theory. The example of the numerical method usage for complex-form surface with hole is showed in fig. 1. The magnetic field of given sources is homogeneous.

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#### Authors:

Dr. Jan Naumenko

Prof. Vladimir Astakhov

Southern Science Centre of RAS, South-Russian State Technical Univ., Budyennovskaya st. 183-29.

346421, Novocherkassk, Russia

Phone: +79054576301

Fax: -

E-mail: [jan@novoch.ru](mailto:jan@novoch.ru), [v.astakhov@mail.ru](mailto:v.astakhov@mail.ru)